### TOSHIBA AMERICA INFORMATION SYSTEMS STORAGE DEVICE DIVISION IRVINE, CALIFORNIA

## MK6026GAX (HDD2194) 2.5-INCH HARD DISK DRIVE USER MANUAL

Rev 02

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## **INTRODUCTION - MK6026GAX (HDD2194)**

### **General Features**

- Rotational speed of 5,400rpm
- 2.5" sized drive
- Fluid Dynamic Bearing (FDB) Motor
- 2 Platter
- 60 Gigabytes\*
- 9.5mm High
- 12ms Average Seek Time
- ATA-2,3,4,5,6 Interface
- Supports high transfer rates of 100 MB/sec
- 16MB Buffer
- MTTF 300,000 Hours

<sup>\*</sup>Toshiba defines a megabyte (MB) as 1,000,000 bytes and a gigabyte (GB) as 1,000,000,000 bytes.

### SETUP - MK6026GAX (HDD2194)



**Caution**: Your Hard Disk Drive is a precision device and even a small drop onto any surface can cause damage. Electronstatic discharge can also damage the drive. You should ground yourself prior to handling the drive.

### **Master/Slave Settings**

Your Toshiba Hard Disk Drive can be configured as either a "Master" or "Slave" unit. Master configuration is used for all single drive applications, and master or slave configuration (only one of each per port) is used for two drive applications. Use the information in the following table before setting drive as Master or Slave.

Master configuration is obtained by setting jumpers A, B, C & D open (no jumper present). Slave configuration is obtained by setting jumpers C-D. When B-D jumper is installed, the drive is configured as cable select. If pin 28 = Low, the drive is "Master", if pin 28 - High, the drive is "Slave".

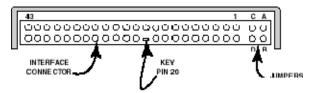


Figure 1.HDD Jumper Locations

JUMPER	P28	DRIVE
No Jumper	-	Master Drive
C-D Jumper	-	Slave Drive
B-D Jumper	LOW	Master Drive
B-D Jumper	HIGH	Slave Drive
Prohibit A-B Jumper	-	-
Prohibit A-C Jumper	-	-

#### **Installation Notes**

- The drive should be mounted carefully on the surface of 0.1mm or less flatness to avoid excessive distortion.
- In order to prevent short-circuit under any circumstances, a space of 0.5mm or more should be kept under the PCB.
- Space should be kept around the drive to avoid any contact with other parts, which may occur
  due to shock or vibration.
- The temperature of the top cover and the base must always be kept under 60C to maintain the required reliability.
- Be sure not to cover the breathing hole to keep the pressure inside the drive at a certain level
- Do not apply any force to the top cover, except the screw areas on top cover. Maximum force to the specified area is 2N.
- The drive contains several parts which may be easily damaged by ESD (Electric Static Discharge). Avoid touching the interface connector pins and the surface of PCB. Be sure to use ESD proof wrist strap when handling drive.
- The four mounting screws should be tightened equally with 0.3N-m (3kgf-cm) torque. The depth should be 3.0mm minimum and 3.5mm maximum.

### **Placing Hard Drive inside your Computer**

- Determine mounting configuration (the drive can be mounted in either a horizontal or vertical orientation)
- Configure drive for system application.
- Configure the adapter board for the specific system application (if required).
- Install adapter board into an unused PC/AT 16 bit slot (if required).
- Install the I/F cable to the system's 44 pin connector port or adapter board. Ensure pin 1 is oriented correctly, (pin 1 on the cable is usually identified by a red or blue strip.)
- Set correct drive type in system CMOS
- Refer to applicable manuals for software installation instructions.





Figure 2.HDD Mounting Holes

## **USING THE HARD DISK DRIVE – MK6026GAX (HDD2194)**

### **Backing up Data Files**

To avoid data loss, regularly back up the data files on the hard disk drive.

## **TROUBLESHOOTING – MK6026GAX (HDD2194)**

Problem	Solution
My system is not able to recognize all available capacity on my Hard Disk Drive. What do I need to do to utilize the complete hard drive?	There are some systems that are unable to recognize the new larger Hard Drives on the market. 3rd party software is available that breaks the "capacity barrier". Some suggestions are EZ Drive by Micro House and Disk Manager DiskGo by Ontrack. Check with your local computer/software supplier for availability or contact the software manufacturer.
How do I install my 2.5" Toshiba Hard Drive into my desktop or tower system?	You will need a HDD mounting kit in order to install a Toshiba 2.5" drive into your desktop or tower system.  Contact your local computer supplier for kit availability.

### SPECIFICATIONS -MK6026GAX (HDD2194)

#### General

Model MK6026GAX (HDD2194)

Interface ATA-2/3/4/5/6

Motor Fluid Dynamic Bearing (FDB)

### **Functionality**

Formatted Capacity 60.012GB\*
Rotational Speed 5,400rpm
Avg. Rotational Latency 5.55/ms
Spin-up Time 4sec (typical)

Buffer 16MB Seek Time (Average) 12

Internal Transfer Rate 258 ~ 394 Mbits/sec (max)

Host Transfer Rate 100Mbytes/sec

#### **Internal Drive Characteristics**

Number of Disks 2 Number of Read/Write Heads 4 Track Density (TPI) 88.8k User Data Cylinders 54,000 Logical Cylinders 16,383 Logical Heads 16 Logical Sectors/track 63 Bytes per Sector 512

Logical Blocks (LBA) 117,310,240

#### Reliability

Preventative maintenance None

Nonrecoverable read errors 1 error per 10<sup>13</sup> bits read

#### **Electrical**

Voltage 5V 5%

#### **Power Consumption**

Start 5.0W typ
Seek 2.9W typ
Read/Write 2.5W typ
Sleep 0.1W typ
Energy Consumption Efficiency 0.021W/GB avg

Shock

Operating 1,960m/s² (200G)(2msec) Non-Operating 7,840m/s² (800G)(1msec)

<sup>\*</sup>Toshiba defines a megabyte (MB) as 1,000,000 bytes and a gigabyte (GB) as 1,000,000,000 bytes.

### **Physical**

 Height
 0.37" (9.5mm)

 Width
 2.75" (69.85mm)

 Depth
 3.94" (100mm)

 Weight
 3.56oz (101g) typ

### Regulatory

The drive satisfies the following standards: Underwriters Laboratories (UL) 1950

Canadian Standard Association (CSA) C22.2 No.220 No. 950

TUV Rheinland EN 60 950

EMC - EN50081-1 EN55022: 1988 Class B

EN60555-2: 1987+ A1 EN60555-3: 77A (Co) 38

EMC - EN50082-1 IEC 801-2: 1991

EIC 801-3: 1994 IEC 801-4: 1988

### **DRIVE CONNECTORS – MK6026GAX (HDD2194)**

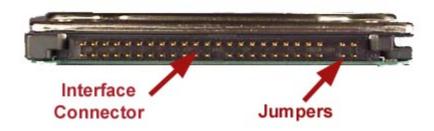


Figure 1.MK6026GAX HDD Rear View - Connectors

### **Interface Connector**

Drive Side Connector Yamaichi GAP050K11617 or equivalent

Recommended Host Side Connector

Board Straight type: Berg 86455-044 86456-044 or equivalent

Cable Berg 89361-044 or equivalent

#### **Recommended Cable Characteristics**

Standard diameter 0.32mm (28AWG)
Characteristics impedance 100 - 1320hm
Max Length 0.46mm (max)
Capacitance 35pF (max)

<sup>\*</sup> cable is not included with drive

### **Interface Pin Assignment**

DRIVE INTERFACE SIGNALS				
PIN	SIGNAL	PIN	SIGNAL	
1	RESET	2	GROUND	
3	DD 7	4	DD 8	
5	DD 6	6	DD 9	
7	DD 5	8	DD 10	
9	DD 4	10	DD 11	
11	DD 3	12	DD 12	
13	DD 2	14	DD 13	
15	DD 1	16	DD 14	
17	DD 0	18	DD 15	
19	GROUND	20	KEY	
21	DMARQ	22	GROUND	
23	DIOW/STOP	24	GROUND	
25	DIOR/ -DMARDY HSTROBE	26	GROUND	
27	IORDY/ -DMARDY/- DSTROBE	28	CSEL	
29	DMACK	30	GROUND	
31	INTRQ	32	IOCS16	
33	DA1	34	PDIAG	
35	DA0	36	DA 2	
37	CS0	38	CS1	
39	DASP	40	GROUND	
41	+5V (LOGIC)	42	+5V (MOTOR)	
43	GROUND	44	RESERVED	
Note: 5	Note: Symbol () in front of signal indicates negative logic.			

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