ADJUSTABLE SPEED DRIVES



Reliable & Configurable

Reliable

Toshiba has manufactured pulse-width modulated drives since 1981 and is one of the few companies that manufactures both motors and drives in the same facility. Because of this, Toshiba has the knowledge to develop and manufacture the most powerful, efficient, and motor-friendly adjustable speed drives available.

Toshiba produces one of the most reliable and rugged adjustable speed drives in the industry. Users can rely on Toshiba drives working for years beyond their warranty.

The Q9 is no exception — it is built to last. Toshiba uses oversized transistors and heavy-duty DC bus capacitors to extend the drive's life. The Q9 is listed at 100,000 AIC interrupting capacity. The drive is also designed to operate in environments from -10° to 40°C at elevations up to 3,300 feet.



Integrated Enclosure

Configurable

The Q9 is not only a monster in durability and dependability, but also simple to use. The electronic operator interface (EOI), with its LCD display and simple keypad layout, allows for quick and easy menu and parameter navigation. Toshiba even provides optional Windows®-based software to help with Q9 programming and monitoring.

With eight digital inputs, three digital outputs, three analog inputs, two analog outputs, EOI, and various communication protocol options, the Q9 allows for flexibility in controlling and monitoring the drive.

My Function is a Q9 feature that allows the user to access built-in PLC-type logic. My Function provides basic logic programming without the need for an external PLC.

HVAC-Minded

Designed for HVAC Systems

The Q9 ASD is designed for HVAC systems offering many popular features needed in the industry. It comes equipped with a fire-speed circuit that forces the drive to run at a preset speed during a smoke purge. The Q9 also provides a damper-permissive function that can be used to protect from over-pressuring ductwork.

A user can set a low-output disable time to force the drive to zero-speed if the drive runs at the lower limit frequency for a specified time. This option helps reduce energy costs.

PID Control

A built-in proportional/integral/derivative (PID) controller, used to regulate a process without the need for external control devices, comes standard with the Q9. In addition, the wire-break function trips the drive if the feedback signal drops below specified levels. This prevents the drive from accelerating to maximum speed and helps protect the system.



Communications

The Q9 supports many common protocols used in HVAC applications including:

- BACnet (MS/TP)®
- LonWorks[®]
- Metasys N2[®]
- Modbus RTU[®]
- APOGEE FLN®

Internal Communication Option Cards

System-Friendly

The Q9 includes multiple features in its standard design that protects the drive, your equipment, and your systems.

Alarms & Faults

The Q9 provides various alarms and fault-notifications that serve to alert the user when poor operating conditions are present. This capability not only protects your drive but also protects the motor that is connected to it.

Equipment Friendly

The Q9's speed search function can detect the speed and direction of a spinning motor and start smoothly without tripping. This drive feature proves especially useful when trying to start a motor after a momentary power outage or in the case of a free-wheeling fan.

Adjustable acceleration/deceleration times and stall capabilities allow for minimal stress on fans, pumps, belts, and pulleys.

The Q9 is capable of programming up to three different skip frequencies. User-selected frequencies may be "skipped" to avoid the negative effects of mechanical resonance.

ASD Pro Software

Toshiba offers downloadable software that can be used to interface with the Q9 at no additional cost. The software can be used to program and control the Q9, download parameter sets, and monitor real-time conditions.



Integrated Enclosure & Extender Box

Toshiba allows you to "build your own drive" by including many of the popular features requested by the HVAC market as choices for your own standard package. The configurations you can choose include line reactors for input power-conditioning and harmonic mitigation, as well as the choice between two or three-contactor bypasses to allow for across-the-line motor operation.



Integrated Enclosure Dimensions								
	Without Reactor							
230 V	3 to 7.5 HP	10 to 25 HP						
460 V	3 to 15 HP	20 to 40 HP						
Height (in.)	28.5	45.5						
Width (in.)	16.1	16.1						
Depth (in.)	10.6	13.9						

Integrated Enclosure

"Build your own drive" uses a standard NEMA 1 enclosure that is available with the following options:

- Input Circuit Breaker
- Two-Contactor Bypass
- Three-Contactor Bypass
- 3% AC Line Reactor
- 5% AC Line Reactor
- DC Link Reactor

Extender Box

The extender box includes the same options for line reactors and bypass configurations as the integrated enclosure. The extender box is connected to the bottom of the standard Q9 power unit, and the entire assembly is NEMA 1 rated.

		Bypass Box	Dimensions					
	Without	Reactor	With Reactor					
230 V	30 HP 40 HP			30 HP	40 HP			
460 V		50 to 100 HP	50 to 60 HP		75 to 100 HP			
Height (in.)*	35.5	36.3	36.3	40.5	41.3			
Width (in.)	16.0	16.0	16.0	16.0	16.0			
Depth (in.)	12.5	12.5	12.5	12.5	12.5			

^{*} Height does not include power unit dimension.

Layout & Enclosure

LCD Display

Displays Configuration Information, Performance Data, and Diagnostic Information

Option Card Status LEDs

Shows Stackable Option Card Status LEDs When Options are Installed

LOCAL/REMOTE Key

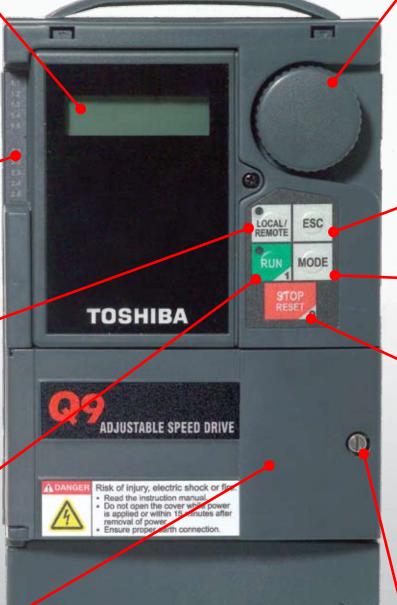
Toggles System to and from Local/Remote Modes; LOCAL/REMOTE Key Light Illuminates Green While in Local Mode

RUN Key

Issues Run Command While in Local Mode; RUN Key Light Illuminates Red While Running and Green While Stopped

Panel Door

Allows Easy Access to Control Terminal Strip



Rotary Encoder

Accesses the Q9 Menu Selections, Changes Parameter Values, and Performs Enter Function; Up and Down Functions Operated by Rotating Encoder

ESCAPE Key

Returns System to Previously Viewed Menu Item

MODE Key

Provides a Means to Access Five Root Menus

STOP/RESET Key

Issues Off Command While in Local Mode; Initiates Emergency-Off if Pressed Twice Quickly; Resets Active Faults and/or Alarms if Pressed Twice Quickly

Panel Locking Screw

Allows for Simple Front-Panel Locking and Unlocking

Meets or Exceeds Your Specifications

				Q9	Stand	dard S	Specif	icatio	ns					
Input Voltage								230 V						
HP Rating		1	2	3	5	7.5	10	15	20	25	30	40	50	60
Current Rating		4.8	7.8	11	17.5	25.3	32.2	48.3	62.1	78.2	92	120	150	177
Input Voltage		7.0	7.0		17.0				ree-Phas		02	120	100	177
HP Rating		1	2	3	5	7.5	10	15	20	25	30	40	50	60
Current Rating		2.1	3.4	4.8	7.6	11	14	21	27	34	40	52	65	77
HP Rating		75	100	125	150	200	250	300	350	400	40	52	0.5	, , ,
Current Rating		96	124	156	180	240	302	361	414	477				
Current Rating		90	124	150		wer Reg			414	4//				
Input Voltage Ran	000		200 to 24	0 V E0/6				.5	200	to 490 \/	50/60 H-	Thron D	haaa	
Power Terminals	ige	200 to 240 V, 50/60 Hz, Three-Phase 380 to 480 V, 50/60 Hz, Three-Phase Input (L1/R, L2/S, L3/T), Output (T1/U, T2/V, T3/W), DCL (PO, PA), DC Bus (PA, PC)												
Voltage Tolerance		±10% ±2%												
Frequency Tolera	nce	±2%			Co	ntral Cna	oificatio							
Output Method		Cino Mo	vo Dulgo	Midth Ma		ntrol Spe	cilicatio	iis						
	, Dongo		ve Pulse-	vviatri ivic	ouialeu s	system								
Output Frequency	Range	0 to 299		\	Γ		T D		11	1/1 0 -		IV \ //6 F		0 - 411
V/Hz Pattern								bost, Sen	sor-Less '	vector Co	ntroi (Spe	eed), V/f F	rive-Point	Settino
Overland Come	Datin		ent Magne				:1							
Overload Current			ontinuous											
Frequency Contro												Operated		meter
Frequency Accura					kimum Oı	utput Fred	quency; D	igital Inpu	ıt: ±0.01%	of ±0.02	2 Hz of C	output Fre	quency	
Frequency Resolu	ution	Operation	n Panel:	0.01 Hz										
Acceleration/Dece	eleration	0.1 to 60	00 Secor	nds										
Analog Inputs	11 ==											nd One ±	10 VDC	
Analog Outputs		Two Pro	grammab	le to 57 F	unctions	(One Swi	tchable 0	to 10 VD	C/0 to 20	mA, and	One 0 to	1 mA)		
Discrete Inputs		Eight Pro	ogramma	ble to 41	Functions	3		i carie						
Sink/Source Switch	ching	Ability to	Switch B	etween S	ink Logic	and Sou	rce Logic							
Discrete Outputs		Three Pr	ogramma	able to 83	Function	s (Two Fo	orm-A and	One For	m-C); Ou	tputs Rat	ed at 2 A	120 VAC	, 2 A/30 V	DC
DID (Cot Doint Co	ntrol)	Adjustme	ent of Pro	portional	Gain, Inte	egral Time	e, Differer	ntial Time	and Dela	av Filter				
LID (261 LOUIT CO		Adjustment of Proportional Gain, Integral Time, Differential Time, and Delay Filter DC Braking, Over-Flux Braking												
PID (Set Point Co Braking Control	111101)			•	king									
Braking Control Communication P		DC Brak		-Flux Bra										
Braking Control	orts	DC Brak Two-Wir	ing, Over e/Four-W	-Flux Bra ire RS48	5									
Braking Control Communication P	orts	DC Brak Two-Wir	ing, Over	-Flux Bra ire RS48	5		RTU®, A							
Braking Control Communication P Communication P	orts rotocol	DC Brak Two-Wird BACNet	ing, Over e/Four-W [®] , LonWo	-Flux Bra ire RS48 rks [®] , Met	asys N2®	, Modbus	RTU®, A	POGEE I	FLN®		ctronic Th	nermal Mo	otor Prote	ction
Braking Control Communication P Communication P Protective Function	rotocol	DC Brak Two-Wire BACNet	ing, Over e/Four-W ®, LonWo age Stall,	-Flux Bra ire RS48 rks [®] , Met	asys N2®	, Modbus	RTU®, A	POGEE I	FLN®		ctronic Th	nermal Mo	otor Prote	ction
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Braking Control Communication P Communication P Protective Function Interrupting Curre Faults Retry Restart EOI Display Keys Rotary Encoder Monitoring Display Units Temperature Relative Humidity Altitude 230 V 460 V Frame	Ports Protocol ons Int Rating 1 to 2 HP 1 to 3 HP 2	DC Brak Two-Win BACNet Overvolt 100,000 Overcurn Commun Error, Ur Ability to Ability to Ability to Full-Eng LOCAL/I Encoder Monitors Program -10° to 4 Maximun 1000 Me 3 to 5 HP 5 to 7.5 HP 3	ing, Over e/Four-W e/	Overcurr Overhea ime-Out, A ge ertain Fau peed and it LCD Di , ESC, RI grated En Condition isplay Pe on-Conde ess 10 HP 15 to 20 HP 5A	t, ASD ON Analog-In Illian Sular Stall, Illian Sular S	Protes Protes Critical (Section of Section o	RTU®, A ction Skip) Fred Motor Over Inal Over Programm Wheeling I face (RESET Incy and F Amps Inchidential I	POGEE I quencies, prioad, Ov voltage, E nable Up Motor and Parameter s 40 to 60 HP - 7B	Ride-Thromagness ervoltage mergency to 10 Return Start into	ough, Ele , Overtorn y Stop, In ries o Motor S ents	que, Unde put/Output/Ou	ercurrent, ut Phase I	Ground F Loss, RAM	Fault, M/ROM
Braking Control Communication P Communication P Protective Functic Interrupting Curre Faults Retry Restart EOI Display Keys Rotary Encoder Monitoring Display Units Temperature Relative Humidity Altitude 230 V	Ports Protocol ons Int Rating 1 to 2 HP 1 to 3 HP	DC Brak Two-Win BACNets Overvolt 100,000 Overcurn Commur Error, Ur Ability to Ability to Ability to Full-Eng LOCAL/I Encoder Monitors Program -10° to 4 Maximur 1000 Me 3 to 5 HP 5 to 7.5 HP	ing, Over e/Four-W e/	Overcurr Overhea ime-Out, A ge ertain Fau peed and it LCD Di , ESC, RI grated En Condition isplay Pe on-Conde	t, ASD Over Analog-In Its Autom Direction Splay JN, MOD Iter Key for a serion s	Protes Protes Critical (Section of Section o	RTU®, A ction Skip) Fred Motor Over Inal Over Programm Wheeling I face (RESET Incy and F Amps Inchination Inchinat	POGEE I quencies, prioad, Ov voltage, E nable Up Motor and Parameter s 40 to 60 HP	Ride-Thromagness ervoltage mergency to 10 Return Start into	ough, Ele , Overtorn y Stop, In ries o Motor S ents	que, Unde put/Outpu moothly	ercurrent, ut Phase I	Ground F Loss, RAN	Fault, M/ROM

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