

Data Acquisition

# **UMDAS 0802DA**

USB Data Acquisition Module - 8 Channels of 48kHz 13-bit A/D, 16 DIO, with 2 channels of 12-bit D/A

# **USER'S MANUAL**

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# **Table of Contents**

Preface	vi
About this User's Guide  What you will learn from this user's guide	
Conventions in this user's guide	VI
Chapter 1 Introducing the UMDAS 0802DA	1-1
UMDAS 0802DA block diagram	
Software features	
Connecting a UMDAS 0802DA to your computer is easy	1-3
Chapter 2 Installing the UMDAS 0802DA	2.4
What comes with your UMDAS 0802DA shipment?	
Hardware	
Additional documentation	
Unpacking the UMDAS 0802DA	2-2
Installing the software	2-2
Installing the hardware	2-2
Calibrating the UMDAS 0802DA	2-3
Chapter 3 Functional Details	2.4
Theory of operation - analog input acquisition modes	
Software paced mode	
Continuous scan mode	3-1
External components	
USB connector	
Screw terminal wiring	
Main connector and pin out	
Analog input terminals (CH0 IN - CH7 IN)	
Digital I/O terminals (Port A0 to A7, and Port B0 to B7)	
Power terminals	
External trigger terminal	
+2.5VREF terminal	
SYNC terminal	
Ground terminals	
Accuracy	
Synchronizing multiple units	
Chapter 4	
Specifications	4-1
Analog input	
Analog output	
Digital input/output	4-3
External trigger	4-4
External clock input/output	4-4
Counter section	4-4

Non-volatile memory	4-5
Microcontroller	4-5
Power	
General	4-6
Environmental	4-6
Mechanical	4-6
Main connector and pin out	4-6
4-channel differential mode	4-6
8-channel single-ended mode	4-7

# **About this User's Guide**

# What you will learn from this user's guide

This user's guide explains how to install, configure, and use the UMDAS 0802DA, and also refers you to related documents available on our web site, and to technical support resources.

# Conventions in this user's guide

#### For more information on ...

Text presented in a box signifies additional information and helpful hints related to the subject matter you are reading.

Caution!	Shaded caution statements present information to help you avoid injuring yourself and others, damaging your hardware, or losing your data.
<#:#>	Angle brackets that enclose numbers separated by a colon signify a range of numbers, such as those assigned to registers, bit settings, etc.
bold text	<b>Bold</b> text is used for the names of objects on the screen, such as buttons, text boxes, and check boxes. For example:  1. Insert the disk or CD and click the <b>OK</b> button.
italic text	<i>Italic</i> text is used for the names of manuals and help topic titles, and to emphasize a word or phrase. For example:
	The <i>Insta</i> Cal® installation procedure is explained in the <i>Quick Start Guide</i> .
	Never touch the exposed pins or circuit connections on the board

# **Introducing the UMDAS 0802DA**

This user's guide contains all of the information you need to connect the UMDAS 0802DA to your computer and to the signals you want to measure. The UMDAS 0802DA is part of the CyberResearch™ brand of USB-based data acquisition products.

The UMDAS 0802DA is a USB 2.0 full-speed, device that is supported under popular Microsoft<sup>®</sup> Windows<sup>®</sup> operating systems. The UMDAS 0802DA is fully compatible with both USB 1.1 and USB 2.0 ports. Refer to the "Be sure you are using the latest system software" note in Chapter 2, "Installing the UMDAS 0802DA," to make sure you are using the latest USB drivers.

The UMDAS 0802DA features eight analog inputs, two 12-bit analog outputs, 16 digital I/O connections, and one 32-bit external event counter.

The analog inputs are software configurable for either eight 13-bit single-ended inputs or four 14-bit differential inputs. The 16 digital I/O lines are independently selectable as input or output in two 8-bit ports. The 32-bit counter can count TTL pulses. A SYNC (synchronization) input/output line allows you to pace the analog input acquisition of one USB module from the clock output of another.

The UMDAS 0802DA is powered by the +5 volt USB supply from your computer. No external power is required.

The UMDAS 0802DA is shown in Figure 1-1. I/O connections are made to the screw terminals located along each side of the UMDAS 0802DA.



Figure 1-1. UMDAS 0802DA

# UMDAS 0802DA block diagram

UMDAS 0802DA functions are illustrated in the block diagram shown here.

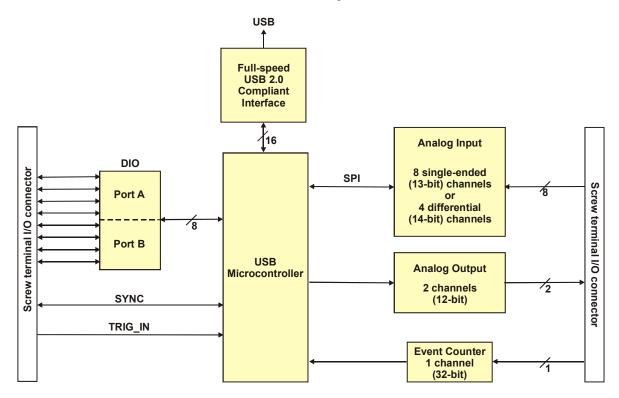


Figure 1-2. UMDAS 0802DA functional block diagram

#### **Software features**

For information on the features of *Insta*Cal and the other software included with your UMDAS 0802DA, refer to the *Quick Start Guide* that shipped in PDF format on the CD which accompanies your device.

### Connecting a UMDAS 0802DA to your computer is easy

Installing a data acquisition device has never been easier.

- The UMDAS 0802DA relies upon the Microsoft Human Interface Device (HID) class drivers. The HID class drivers ship with every copy of Windows that is designed to work with USB ports. We use the Microsoft HID because it is a standard, and its performance delivers full control and maximizes data transfer rates for your UMDAS 0802DA. No third-party device driver is required.
- The UMDAS 0802DA is plug-and-play. There are no jumpers to position, DIP switches to set, or interrupts to configure.
- You can connect the UMDAS 0802DA before or after you install the software, and without powering down your computer first. When you connect an HID to your system, your computer automatically detects it and configures the necessary software. You can connect and power multiple HID peripherals to your system using a USB hub.
- You can connect your system to various devices using a standard four-wire cable. The USB connector replaces the serial and parallel port connectors with one standardized plug and port combination.
- You do not need a separate power supply module. The USB automatically delivers the electrical power required by each peripheral connected to your system.
- Data can flow two ways between a computer and peripheral over USB connections.

# Installing the UMDAS 0802DA

# What comes with your UMDAS 0802DA shipment?

As you unpack your UMDAS 0802DA, verify that the following components are included.

#### **Hardware**

UMDAS 0802DA



■ USB cable (2 meter length)



#### Additional documentation

In addition to this hardware user's guide, you should also receive the *Quick Start Guide* (available in PDF on the software CD that ships with your device. This document supplies a brief description of the software you received with your UMDAS 0802DA and information regarding installation of that software.

### **Unpacking the UMDAS 0802DA**

As with any electronic device, you should take care while handling to avoid damage from static electricity. Before removing the UMDAS 0802DA from its packaging, ground yourself using a wrist strap or by simply touching the computer chassis or other grounded object to eliminate any stored static charge.

If any components are missing or damaged, notify CyberResearch, Inc. immediately by phone, fax, or e-mail:

- Phone: 203-483-9966 and follow the instructions for reaching Tech Support.
- Fax: 203-483-9024 to the attention of Tech Support
- Email: techsupport@cyberresearch.com

### Installing the software

Refer to the *Quick Start Guide* for instructions on installing the software. This booklet is available in PDF format Ton the software CD which accompanies your device.

### Installing the hardware

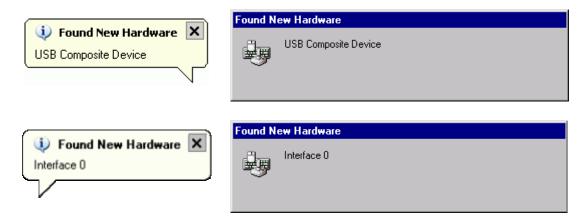
#### Be sure you are using the latest system software

Before you connect the UMDAS 0802DA, make sure that you are using the latest versions of the USB drivers.

Before installing the UMDAS 0802DA, download and install the latest Microsoft Windows updates. In particular, when using Windows XP, make sure you have XP Hotfix KB822603 installed. This update is intended to address a serious error in Usbport.sys when you operate a USB device. You can run Windows Update or download the update from <a href="www.microsoft.com/downloads/details.aspx?familyid=733dd867-56a0-4956-b7fe-e85b688b7f86&displaylang=en">www.microsoft.com/downloads/details.aspx?familyid=733dd867-56a0-4956-b7fe-e85b688b7f86&displaylang=en</a>. For more information, refer to the Microsoft Knowledge Base article "Availability of the Windows XP SP1 USB 1.1 and 2.0 update." This article is available at support.microsoft.com/?kbid=822603.

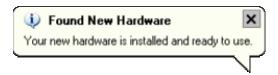
To connect the UMDAS 0802DA to your system, turn your computer on, and connect the USB cable to a USB port on your computer or to an external USB hub that is connected to your computer. The USB cable provides power and communication to the UMDAS 0802DA.

When you connect the UMDAS 0802DA for the first time, a series of **Found New Hardware** popup balloons (Windows XP) or dialogs (other Windows versions) open as the UMDAS 0802DA is detected by your computer.



It is normal for multiple dialogs to open when you connect the UMDAS 0802DA for the first time.

The last popup balloon or dialog states "Your new hardware is installed and ready to use," and the LED on the UMDAS 0802DA should flash and then remain lit. This indicates that communication is established between the UMDAS 0802DA and your computer.



On most computers, you can install up to two UMDAS 0802DA units. If you need to connect more than two UMDAS 0802DAunits to your computer, contact Tech Support by phone (203-483-9966), fax (203-483-9024), or email (techsupport@cyberresearch.com).

**Caution!** Do not disconnect **any** device from the USB bus while the computer is communicating with the UMDAS 0802DA, or you may lose data and/or your ability to communicate with your unit.

#### If the LED turns off

If the LED is illuminated but then turns off, the computer has lost communication with the UMDAS 0802DA. To restore communication, disconnect the USB cable from the computer, and then reconnect it. This should restore communication, and the LED should turn back *on*.

Allow the UMDAS 0802DA to operate for at least 30 minutes before using the device. This warm up time is required to achieve the specified rated accuracy of measurements.

### Calibrating the UMDAS 0802DA

The UMDAS 0802DA is shipped fully calibrated. Calibration coefficients are stored in EEPROM. Return the device to CyberResearch, Inc. when calibration is required. The normal calibration interval is once per year.

# **Functional Details**

### Theory of operation - analog input acquisition modes

The UMDAS 0802DA can acquire analog input data in two different modes – software paced and continuous scan.

#### Software paced mode

In software paced mode, you can acquire one analog sample at a time. You initiate the A/D conversion by calling a software command. The analog value is converted to digital and returned to the computer. You can repeat this procedure until you have the total number of samples that you want from one channel.

The maximum throughput sample rate in software paced mode is system-dependent.

#### Continuous scan mode

In continuous scan mode, you can acquire data from up to eight channels. The analog data is continuously acquired, converted to digital values, and written to an on-board FIFO buffer until you stop the scan. The FIFO buffer is serviced in blocks as the data is transferred from the UMDAS 0802DA to the memory buffer on your computer.

The maximum continuous scan rate of 48 kS/s is an aggregate rate. The total acquisition rate for all channels cannot exceed 48 kS/s. You can acquire data from one channel at 48 kS/s, two channels at 24 kS/s, and four channels at 12 kS/s. You can start a continuous scan with either a software command or with an external hardware trigger event.

# **External components**

The UMDAS 0802DA has the following external components, as shown in Figure 3-1.

- USB connector
- LED
- Screw terminal banks (2)

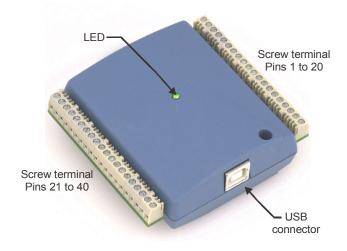


Figure 3-1. UMDAS 0802DA external components

#### **USB** connector

The USB connector is on the right side of the UMDAS 0802DA. This connector provides +5 V power and communication. The voltage supplied through the USB connector is system-dependent, and may be less than 5 V. No external power supply is required.

#### **LED**

The LED on the front of the housing indicates the communication status of the UMDAS 0802DA. It uses up to 5 mA of current and cannot be disabled. Table 3-1 defines the function of the UMDAS 0802DA's LED.

Table 3-1. LED Illumination

LED Illumination	Indication	
Steady green	The UMDAS 0802DA is connected to a computer or external USB hub.	
Blinks continuously	Data is being transferred.	

#### Screw terminal wiring

The UMDAS 0802DA has two rows of screw terminals—one row on the top edge of the housing, and one row on the bottom edge. Each row has 20 connections. Pin numbers are identified in Figure 3-2.



Figure 3-2. UMDAS 0802DA Screw terminal pin numbers

#### Screw terminal - pins 1-20

The screw terminals on the top edge of the UMDAS 0802DA (pins 1 to 20) provide the following connections:

- Eight analog input connections (CH0 IN to CH7 IN)
- Two analog output connections (D/A OUT 0 to D/A OUT 1)
- One external trigger source (**TRIG IN**)
- One SYNC terminal for external clocking and multi-unit synchronization (SYNC)
- One voltage output source (2.5VREF)
- Five analog ground connections (AGND)
- One ground connection (GND)
- One external event counter connection (CTR)

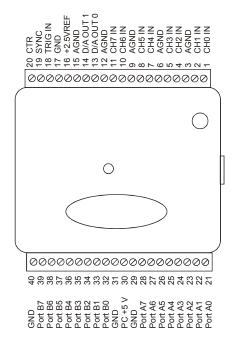
#### Screw terminal - pins 21-40

The screw terminals on the bottom edge of the (pins 21 to 40) provide the following connections:

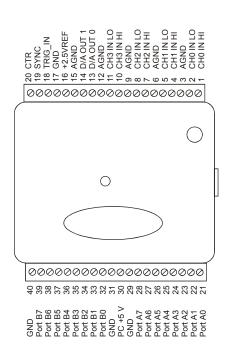
- 16 digital I/O connections (PortA0 to Port A7, and Port B0 to Port B7)
- One power connection (**PC+5 V**)
- Three ground connections (**GND**)

#### Main connector and pin out

Connector type	Screw terminal
Wire gauge range	16 AWG to 30 AWG







4-channel differential mode pin out

#### Analog input terminals (CH0 IN - CH7 IN)

You can connect up to eight analog input connections to the screw terminal containing pins 1 to 20 (**CH0 IN** through **CH7 IN**.) Refer to the "Main connector and pin out" diagrams above for the location of these pins.

You can configure the analog input channels as eight single-ended channels or four differential channels. When configured for differential mode, each analog input has 14-bit resolution. When configured for single-ended mode, each analog input has 13-bit resolution, due to restrictions imposed by the A/D converter.

#### Single-ended configuration

When all of the analog input channels are configured for single-ended input mode, eight analog channels are available. The input signal is referenced to signal ground (GND), and delivered through two wires:

- The wire carrying the signal to be measured connects to CH# IN.
- The second wire connects to AGND.

The input range for single-ended mode is  $\pm 10$  V. No other ranges are supported in this mode. Figure 3-3 illustrates a typical single-ended measurement connection.

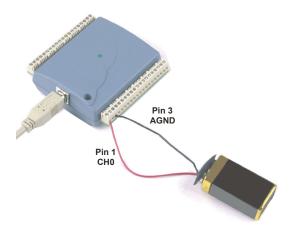


Figure 3-3. Single-ended measurement connection

The following example shows the single-ended measurement data acquired by TracerDAQ.

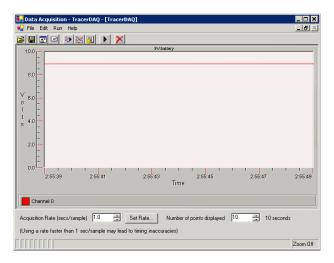


Figure 3-4. Measurement data (9 volt) plotted on TracerDAQ's Strip Chart

#### Single-ended measurements using differential channels

To perform a single-ended measurement using differential channels, connect the signal to "CHn IN HI" input, and ground the associated "CHn IN LO" input.

#### **Differential configuration**

When all of the analog input channels are configured for differential input mode, four analog channels are available. In differential mode, the input signal is measured with respect to the low input.

The input signal is delivered through three wires:

- The wire carrying the signal to be measured connects to CH0 IN HI, CH1 IN HI, CH2 IN HI, or CH3 IN HI.
- The wire carrying the reference signal connects to CH0 IN LO, CH1 IN LO, CH2 IN LO, or CH3 IN LO.
- The third wire connects to GND.

A low-noise precision programmable gain amplifier (PGA) is available on differential channels to provide gains of up to 20 and a dynamic range of up to 14-bits. Differential mode input voltage ranges are  $\pm 20$  V,  $\pm 10$  V,  $\pm 5$  V,  $\pm 4$  V,  $\pm 2.5$  V,  $\pm 2.0$  V, 1.25 V, and  $\pm 1.0$  V.

In differential mode, the following two requirements must be met for linear operation:

- Any analog input must remain in the -10V to +20V range with respect to ground at all times.
- The maximum differential voltage on any given analog input pair must remain within the selected voltage range.

The input [common-mode voltage + signal] of the differential channel must be in the -10 V to +20 V range in order to yield a useful result. For example, you input a 4 V pp sine wave to CHHI, and apply the same sine wave  $180^{\circ}$  out of phase to CHLO. The common mode voltage is 0 V. The differential input voltage swings from 4 V - (-4 V) = 8 V to (-4 V) - 4 V = -8 V. Both inputs satisfy the

-10~V to +20~V input range requirement, and the differential voltage is suited for the  $\pm 10~V$  input range (see Figure 3-5).

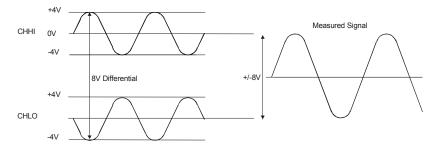


Figure 3-5. Differential voltage example: common mode voltage of 0 V

If you increase the common mode voltage to 11 V, the differential remains at  $\pm 8$  V. Although the [common-mode voltage + signal] on each input now has a range of +7 V to +15 V, both inputs still satisfy the -10 V to +20 V input requirement (see Figure 3-6).

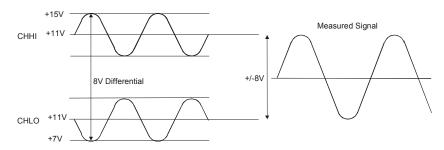


Figure 3-6. Differential voltage example: common mode voltage of 11 V

If you decrease the common-mode voltage to -7 V, the differential stays at  $\pm 8$  V. However, the solution now violates the input range condition of -10 V to +20 V. The voltage on each analog input now swings from -3 V to -11 V. Voltages between -10 V and -3 V are resolved, but those below -10 V are clipped (see Figure 3-7).

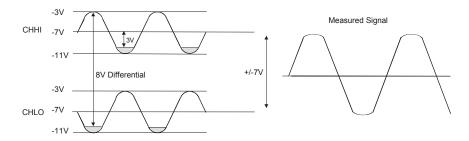


Figure 3-7. Differential voltage example: common mode voltage of -7 V

Since the analog inputs are restricted to a -10 V to +20 V signal swing with respect to ground, all ranges *except*  $\pm 20$ V can realize a linear output for any differential signal with zero common mode voltage and full scale signal inputs. The  $\pm 20$  V range is the exception. You cannot put -20 V on CHHI and 0 V on CHLO since this violates the input range criteria. Table 3-2 shows some possible inputs and the expected results.

СННІ	CHLO	Result
-20 V	0 V	In Valid
-15 V	+5 V	In Valid
-10 V	0 V	-10 V
-10 V	+10 V	-20 V
0 V	+10 V	-10 V
0 V	+20 V	-20 V
+10 V	-10 V	+20 V
+10 V	0 V	+10 V
+15 V	-5 V	+20 V
+20 V	0	+20 V

Table 3-2. Sample inputs and differential results

#### For more information on analog signal connections

For more information on single-ended and differential inputs, refer to the *Guide to Signal Connections* (this document is available on the software CD which accompanies your device.

#### Analog output terminals (D/A OUT 0 and D/A OUT 1)

You can connect up to two analog output connections to the screw terminal pins 13 and 14 (D/A OUT 0 and D/A OUT 1). Refer to the "Main connector and pin out" diagrams on page 3-3 for the location of these pins.

Each channel can be paced individually at rates up to 10,000 updates per second. Both channels can be paced simultaneously using the same time base at 5000 updates per channel. The 0-4.096 V output range provides a convenient 1 mV per LSB when setting the output voltage levels.

#### Digital I/O terminals (Port A0 to A7, and Port B0 to B7)

You can connect up to 16 digital I/O lines to the screw terminal containing pins 21 to 40 (**Port A0** to **Port A7**, and **Port B0** to **Port B7**.) Refer to the "Main connector and pin out" diagrams on page 3-3 for the location of these pins. You can configure each digital port for either input or output.

When you configure the digital bits for input, you can use the digital I/O terminals to detect the state of any TTL level input. Refer to the switch shown in Figure 3-8 and the schematic shown in Figure 3-9. If the switch is set to the +5 V input, Port A0 reads *TRUE* (1). If you move the switch to GND, Port A0 reads *FALSE*.

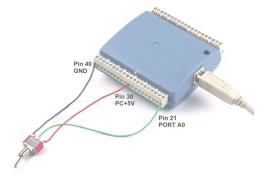


Figure 3-8. Digital connection Port A0 detecting the state of a switch

Figure 3-9. Schematic showing switch detection by digital channel Port A0

#### For more information on digital signal connections

For more information on digital signal connections and digital I/O techniques, available on the software CD which accompanies your device.

#### Power terminals

The PC +5V connection (pin 30) draws power from the USB connector. This terminal is a 5 V output that is supplied by the host computer. Refer to the "Main connector and pin out" diagrams on page 3-3 for the location of this pin.

**Caution!** The +5 V terminal is an output. Do not connect to an external power supply or you may damage the UMDAS 0802DA and possibly the computer.

The maximum total output current that can be drawn from all UMDAS 0802DA connections (power, analog and digital outputs) is 420 mA. This maximum applies to most personal computers and self-powered USB hubs. Bus-powered hubs and notebook computers may limit the maximum available output current to 100 mA.

Just connecting the UMDAS 0802DA to your computer draws 80 mA of current from the USB +5 V supply. Once you start running applications with the UMDAS 0802DA, each DIO bit can draw up to 2.5 mA, and each analog output can draw 15 mA. The maximum amount of +5 V current available for experimental use, over and above that required by the UMDAS 0802DA, is the difference between the *total current requirement* of the USB (based on the application), and the *allowed current draw* of the PC platform (500 mA for desktop PCs and self-powered hubs, or 100 mA for bus-powered hubs and notebook computers). With all outputs at their maximum output current, you can calculate the total current requirement of the UMDAS 0802DA USB +5 V supply as follows:

(UMDAS 0802DA @ 80 mA) + (16 DIO @ 2.5 mA ea) + (2 AO @ 15 mA ea ) = 150 mA

For an application running on a PC or powered hub, the maximum available excess current is 500 mA - 150 mA = 350 mA. This number is the total maximum available current at the PC +5 V screw terminals. CyberResearch, Inc. highly recommends that you figure in a safety factor of 20% below this maximum current loading for your applications. A conservative, safe user maximum in this case would be 280 mA.

Since laptop computers typically allow up to 100 mA, the UMDAS 0802DA in a fully-loaded configuration may be above that allowed by the computer. In this case, you must determine the per-pin loading in the application to ensure that the maximum loading criteria is met. The per-pin loading is calculated by simply dividing the +5 V by the load impedance of the pin in question.

### **External trigger terminal**

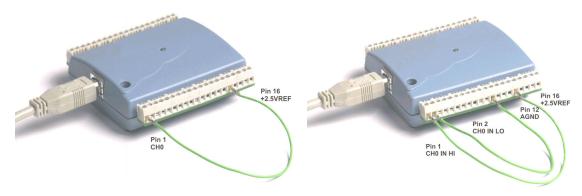
The **TRIG\_IN** connection (pin 18) can be configured for either rising or falling edge. Refer to the "Main connector and pin out" diagrams on page 3-3 for the location of this pin.

#### Counter terminal

The **CTR** connection (pin 20) is input to the 32-bit external event. Refer to the "Main connector and pin out" diagrams on page 3-3 for the location of this pin. The internal counter increments when the TTL levels transition from low to high. The counter can count frequencies of up to 1 MHz.

#### +2.5VREF terminal

The **+2.5VREF** connection (pin 16) is an output terminal that supplies 2.5 volts. The images below show the +2.5VREF pin configured as the voltage source for channel 0.



Single-ended measurement

Differential measurement

#### SYNC terminal

The **SYNC** connection (pin 19) is a bidirectional I/O signal. You can use it for two purposes:

- Configure as an external clock input to externally source the A/D conversions. The SYNC terminal supports TTL-level input signals of up to 48 kHz.
- Configure as an output to synchronize with a second UMDAS 0802DA and acquire data from 16 channels. For
  information on synchronizing multiple units, refer to page 3-11.

#### **Ground terminals**

The four analog ground (**AGND**) connections provide a common ground for all UMDAS 0802DA input channels. Four ground (**GND**) connections provide a common ground for the **DIO**, **TRIG\_IN**, **CTR**, **SYNC** and **PC** +**5V** connections. Refer to the "Main connector and pin out" diagrams on page 3-3 for the location of these pins.

# **Accuracy**

The overall accuracy of any instrument is limited by the error components within the system. Quite often, resolution is incorrectly used to quantify the performance of a measurement product. While "14-bits" or "1 part in 16383" does indicate what can be resolved, it provides little insight into the quality of an absolute measurement. Accuracy specifications describe the actual results that can be realized with a measurement device.

There are three types of errors which affect the accuracy of a measurement system:

- offset
- gain
- nonlinearity

The primary error sources in the UMDAS 0802DA are offset and gain. Nonlinearity is small in the UMDAS 0802DA, and is not significant as an error source with respect to offset and gain.

Figure 3-10 shows an example of an ideal, error-free, UMDAS 0802DA transfer function. The typical calibrated accuracy of the UMDAS 0802DA is range-dependent, as explained in the "Specifications" chapter of this document. We use a  $\pm 10$  V range here as an example of what you can expect when performing a measurement in this range.

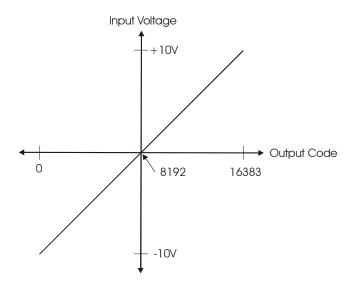


Figure 3-10. Ideal ADC transfer function

The offset error is measured at mid-scale. Ideally, a zero volt input should produce an output code of 8192. Any deviation from this is an offset error.

Figure 3-11 shows an example of a UMDAS 0802DA transfer function with a  $\pm 2.44$  mV offset error affects all codes equally by shifting the entire transfer function up or down along the input voltage axis.

#### The accuracy plots in Figure 3-11 are drawn for clarity and are not drawn to scale.

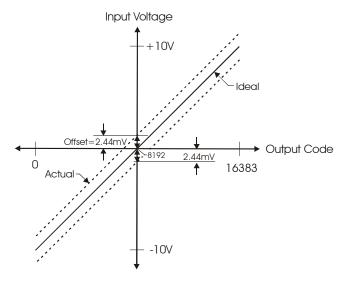


Figure 3-11. ADC transfer function with offset error

Gain error is a change in the slope of the transfer function from the ideal, and is typically expressed as a percentage of full-scale. Gain error is easily converted to voltage by multiplying the full-scale (FS) input by the error.

#### The accuracy plots in Figure 3-12 are drawn for clarity and are not drawn to scale.

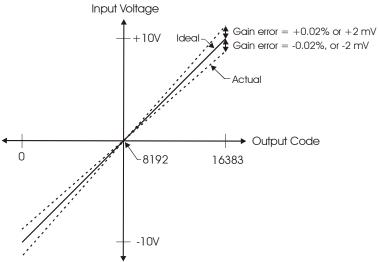


Figure 3-12. ADC Transfer function with gain error

Figure 3-12 shows an example of a UMDAS 0802DA transfer function with a calibrated gain error of  $\pm 0.02\%$ , or  $\pm 2$  mV. This means that at full scale, neglecting the effect of offset for the moment, the measurement would be within 2 mV of the actual value. Note that gain error is expressed as a ratio. Values near  $\pm FS$  are more affected from an absolute voltage standpoint than are values near mid-scale, which see little or no voltage error.

Combining these two error sources in Figure 3-13, we have a plot of the error band of the UMDAS 0802DA for the  $\pm 10 \text{ V}$  range. This is a graphical version of the typical accuracy specification of the product.

#### The accuracy plots in Figure 3-13 are drawn for clarity and are not drawn to scale

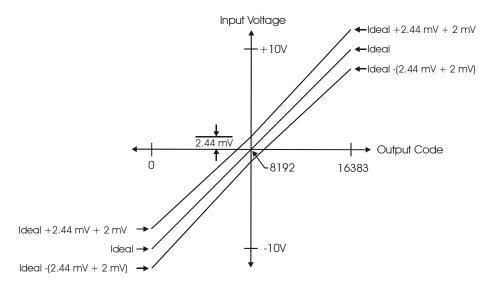


Figure 3-13. Error band plot

### UMDAS 0802DA channel gain queue feature

The UMDAS 0802DA's channel gain queue feature allows you to set up a scan sequence with a unique per-channel gain setting and channel sequence.

The channel gain queue feature removes the restriction of using an ascending channel sequence at a fixed gain. This feature creates a channel list which is written to local memory on the UMDAS 0802DA. Each element of the channel list is made up of a channel number and range setting. An example of a four-element list is shown in Table 3-3.

 Element
 Channel
 Range

 0
 CH0
 BIP10V

 1
 CH3
 BIP5V

 2
 CH1
 BIP10V

 3
 CH2
 BIP1V

Table 3-3. Sample channel gain queue list

When a scan begins with the gain queue enabled, the UMDAS 0802DA reads the first element, sets the appropriate channel number and range, and then acquires a sample. The properties of the next element are then retrieved, and another sample is acquired. This sequence continues until all elements in the gain queue have been selected. When the end of the channel list is detected, the sequence returns to the first element in the list.

This sequence repeats until the specified number of samples is gathered. You must carefully match the gain to the expected voltage range of the associated channel — otherwise, an over range condition can occur. Although this condition does not damage the UMDAS 0802DA, it does produce a useless full-scale reading. It can also introduce a long recovery time from saturation, which can affect the next measurement in the queue.

# Synchronizing multiple units

You can connect the SYNC pin of two UMDAS 0802DA units together in a master/slave configuration and acquire data from the analog inputs of both devices using one clock.

By default, the SYNC pin (pin 19) is set for pacer output, and sends the internal pacer A/D clock signal to the screw terminal. You can use this signal as a clock input to a second USB unit by connecting it to the SYNC pin of the second USB unit.

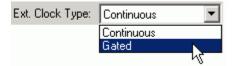
When used as a clock input, the SYNC pin operates in one of two modes – *Continuous* or *Gated*. The mode is software-selectable using *Insta*Cal.

- In the default *Continuous* mode, the UMDAS 0802DA ignores the first clock pulse in order to ensure adequate setup time.
  - Use Continuous mode if the unit is being paced from a continuous clock source, such as a generator.
- In the *Gated* mode, it is assumed that the clock signal will be held off for an adequate amount of time for setup to occur. No clock pulses are ignored.
  - Use Gated mode if you want to use the UMDAS 0802DA unit as a slave, and the source of the external clock is another USB unit.

To synchronize a master UMDAS 0802DA with a slave UMDAS 0802DA and acquire data from the analog inputs of both devices using one clock, follow the steps below.

- 1. Connect the SYNC pin of the master UMDAS 0802DA to the SYNC pin of the slave UMDAS 0802DA.
- 2. Run InstaCal.
- 3. From the PC Board List on the InstaCal main form, double-click on the UMDAS 0802DA you want to use as a slave. The Board Configuration dialog opens.

**4.** Select *Gated* from the **Ext. Clock Type** drop-down list.



5. Set the Universal Library EXTCLOCK option with cbAInScan () /AInScan for the slave UMDAS 0802DA to enable pacing from the master USB device.

This *Insta*Cal option does not affect internally paced acquisition. It only affects scans that use the EXTCLOCK option.

An example of a master/slave configuration is shown here.

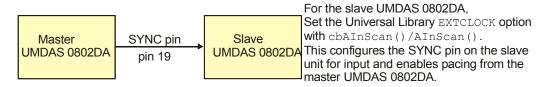


Figure 3-14. Configuring for synchronous data acquisition

When you are operating one UMDAS 0802DA, do not set the EXTCLOCK clock for A/D pacing.

option unless you are using an external

# **Specifications**

Typical for 25°C unless otherwise specified. Specifications in *italic text* are guaranteed by design.

# **Analog input**

Table 4-1. Analog input specifications

Parameter	Conditions	Specification
A/D converter type		Successive approximation type
Input voltage range for linear operation, single-ended mode	CHx to GND	±10 volts (V) max
Input common-mode voltage range for linear operation, differential mode	CHx to GND	-10 V min, +20 V max
Absolute maximum input voltage	CHx to GND	±28 V max
Input current (Note 1)	Vin = +10 V	70 microamperes (μA) typ
	Vin = 0 V	-12 μA typ
	Vin = -10 V	–94 μA typ
Number of channels		8 single-ended / 4 differential, software selectable
Input ranges, single-ended mode		±10 V, G=2
Input ranges, differential mode		±20 V, G=1
		±10 V, G=2
		±5 V, G=4
		±4 V, G=5
		±2.5 V, G=8
		±2.0 V, G=10
		±1.25 V, G=16
		±1.0 V, G=20
		Software selectable
Throughput (Note 2)	Software paced	250 samples per second (S/s) typ, PC-dependent
	Continuous scan	48 kilosamples per second (kS/s)
Channel gain queue	Up to 16 elements	Software configurable channel, range, and gain.
Resolution (Note 3)	Differential	14-bits, no missing codes
	Single-ended	13-bits
Integral linearity error		±2 least significant bit (LSB) typ
Differential linearity error		±0.5 LSB typ
Absolute Accuracy Long Term Drift	±20V range	$\pm 3$ LSB typ. (delta t = 1000 hrs)
(Note 4)	±4V range	$\pm 6LSB$ typ. (delta t = 1000 hrs)
	±1V range	$\pm 8LSB \text{ typ. (delta t} = 1000 \text{ hrs)}$
2.5VREF accuracy (pin 16)		±36.25 mV max.
2.5VREF output current (pin 16)	Source	5 mA max.
	Sink	20 μA min, 100 μA typ
Trigger source	Software selectable	External digital: TRIG_IN

Note 1: Input current is a function of applied voltage on the analog input channels. For a given input voltage,  $V_{in}$ , the input leakage is approximately equal to  $(8.181*V_{in}-12)~\mu A$ .

**Note 2:** Maximum throughput scanning to PC memory is machine dependent. The rates specified are for Windows XP only. Maximum rates on operating systems that predate XP may be less and must be determined through testing on your machine

**Note 3:** The ADS7871 converter only returns 13-bits (0 to 8192 codes) in single-ended mode.

**Note 4:** Extrapolating the long term drift accuracy specifications will provide the approximate long term drift of the UMDAS 0802DA intermediate input ranges.

Table 4-2. Accuracy, differential mode

Range	Absolute Accuracy 25°C (±mV)	Absolute Accuracy 0 to 50°C (±mV)
±20 V	10.98	49.08
±10 V	7.32	33.42
±5 V	3.66	20.76
±4 V	2.92	19.02
±2.5 V	1.83	14.97
±2 V	1.70	14.29
±1.25 V	1.21	12.18
±1 V	1.09	11.63

Table 4-3. Accuracy, single-ended mode

Range	Absolute Accuracy 25°C (±mV)	Absolute Accuracy 0 to 50°C (±mV)
±10 V	10.98	49.08

Table 4-4. Noise performance, differential mode

Range	Typical counts	Least significant bit <sub>root mean square</sub> (LSB <sub>rms)</sub>
±20 V	8	1.21
±10 V	8	1.21
±5 V	9	1.36
±4 V	10	1.51
±2.5 V	12	1.81
±2 V	14	2.12
±1.25 V	18	2.72
±1 V	22	3.33

Table 4-5. Noise performance, single-ended mode

Range	Typical Counts	LSB <sub>rms</sub>
±10 V	8.0	1.21

# **Analog output**

Table 4-6. Analog output specifications

Parameter	Conditions	Specification
Resolution		12-bits, 1 in 4096
Output range		0 to 4.096 V, 1 mV per LSB.
Number of channels		2
Throughput (Note 5)	Software paced	250 S/s single channel typical, PC dependent
	Single channel, continuous scan	10 kS/s
	Dual channel, continuous scan, simultaneous update	5 kS/s
Power on and reset voltage		0V, ±20 mV typ. (initializes to 000h code)
Output drive	Each D/A OUT	±15 mA
Slew rate		0.8 V/microsecond (μs) typ

**Note 5:** Maximum throughput scanning from PC memory is machine dependent. The rates specified are for Windows XP only. Maximum rates on operating systems that predate XP may be less and must be determined through testing on your machine.

Table 4-7. Analog output accuracy

Range	Accuracy (±LSB)
0 to 4.096 V	4.0 typ, 45.0 max

Table 4-8. Analog output accuracy components

Range	% of FSR (±)	Gain Error at FS (±mV)	Offset (±mV)	Accuracy at FS (±mV)
			(Note 6)	
0 to 4.096 V	0.1 typ, 0.9 max	4.0 typ, 36.0 max	1.0 typ, 9.0 max	4.0 typ, 45.0 max

**Note 6:** Zero-scale offsets may result in a fixed zero-scale error producing a "dead-band" digital input code region.. In this case, changes in digital input code at values less than 0x040 may not produce a corresponding change in the output voltage. The UMDAS 0802DA offset error is tested and specified at code 0x040.

# **Digital input/output**

Table 4-9. Digital I/O specifications

Digital type	CMOS
Number of I/O	16 (Port A0 through A7, Port B0 through B7)
Configuration	2 banks of 8
Pull-up/pull-down configuration	All pins pulled up to Vs via 47 K resistors (default). Positions available for pull-down to ground. Hardware selectable via zero ohm $(\Omega)$ resistors as a factory option.
Input high voltage	2.0 V min, 5.5 V absolute max
Input low voltage	0.8 V max, -0.5 V absolute min
Output high voltage $(IOH = -2.5 \text{ mA})$	3.8 V min
Output low voltage (IOL = 2.5 mA)	0.7 V max
Power on and reset state	Input

# **External trigger**

Table 4-10. Digital trigger specifications

Parameter	Conditions	Specification
Trigger source (Note 7)	External digital	TRIG_IN
Trigger mode	Software selectable	Edge sensitive: user configurable for CMOS compatible rising or falling edge.
Trigger latency		10 μs max
Trigger pulse width		1 μs min
Input high voltage		4.0 V min, 5.5 V absolute max
Input low voltage		1.0 V max, -0.5 V absolute min
Input leakage current		$\pm 1.0 \ \mu A$

**Note 7:** TRIG\_IN is a Schmitt trigger input protected with a 1.5 kilohm ( $k\Omega$ ) series resistor.

# **External clock input/output**

Table 4-11. External clock I/O specifications

Parameter	Conditions	Specification
Pin name		SYNC
Pin type		Bidirectional
Software selectable direction	Output (default)	Outputs internal A/D pacer clock.
	Input	Receives A/D pacer clock from external source.
Input clock rate		48 KHz, maximum
Clock pulse width	Input mode	1 μs min
	Output mode	5 μs min
Input leakage current	Input mode	$\pm 1.0~\mu A$
Input high voltage		4.0 V min, 5.5 V absolute max
Input low voltage		1.0 V max, -0.5 V absolute min
Output high voltage (Note 8)	IOH = -2.5  mA	3.3 V min
	No load	3.8 V min
Output low voltage (Note 8)	IOL = 2.5  mA	1.1 V max
	No load	0.6 V max

**Note 8:** SYNC is a Schmitt trigger input and is over-current protected with a 200  $\Omega$  series resistor.

#### **Counter section**

Table 4-12. Counter specifications

Pin name (Note 9)	CTR
Counter type	Event counter
Number of channels	1
Input type	TTL, rising edge triggered
Input source	CTR screw terminal
Resolution	32 bits
Schmidt trigger hysteresis	20 mV to 100 mV
Input leakage current	$\pm 1~\mu A$
Maximum input frequency	1 MHz
High pulse width	500 ns min
Low pulse width	500 ns min
Input high voltage	4.0 V min, 5.5 V absolute max
Input low voltage	1.0 V max, -0.5 V absolute min

**Note 9:** CTR is a Schmitt trigger input protected with a 1.5K  $\Omega$  series resistor.

### Non-volatile memory

Table 4-13. Non-volatile memory specifications

EEPROM	1,024 bytes		
EEPROM Configuration	Address Range	Access	Description
	0x000-0x07F	Reserved	128 bytes system data
	0x080-0x1FF	Read/write	384 bytes cal data
	0x200-0x3FF	Read/write	512 bytes user area

#### **Microcontroller**

Table 4-14. Microcontroller specifications

Туре	High performance 8-bit RISC microcontroller	
Program memory	16,384 words	
Data memory	2,048 bytes	

#### **Power**

Table 4-15. Power specifications

Parameter	Conditions	Specification
Supply current (Note 10)		80 mA
+5V USB power available	Connected to self-powered hub	4.5 V min, 5.25 V max
(Note 11)	Connected to externally-powered root port hub	
	Connected to bus-powered hub	4.1 V min, 5.25 V max
Output current (Note 12)	Connected to self-powered hub	420 mA max
	Connected to externally-powered root port hub	
	Connected to bus-powered hub	20 mA max

**Note 10:** This is the total current requirement for the UMDAS 0802DA which includes up to 10 mA for the status LED.

**Note 11:** Self-powered hub refers to a USB hub with an external power supply. Self-powered hubs allow a connected USB device to draw up to 500 mA.

Root port hubs reside in the PC's USB host controller. The USB port(s) on your PC are root port hubs. All externally powered root port hubs (desktop PCs) provide up to 500 mA of current for a USB device. Battery-powered root port hubs provide 100 mA or 500 mA, depending upon the manufacturer. A laptop PC that is not connected to an external power adapter is an example of a battery-powered root port hub.

Bus powered hubs receive power from a self-powered or root port hub. In this case the maximum current available from the USB +5 V is 100 mA. The minimum USB +5 V voltage level can be as low as 4.1 V.

Note 12: Output current refers to the total amount of current that can be sourced from the USB +5 V, analog outputs and digital outputs.

# General

Table 4-16. General specifications

Parameter	Conditions	Specification
Device type		USB 2.0 full speed
Device compatibility		USB 1.1, USB 2.0

# **Environmental**

Table 4-17. Environmental specifications

Operating temperature range	0 to 70 °C
Storage temperature range	−40 to 70 °C
Humidity	0 to 90% non-condensing

### Mechanical

Table 4-18. Mechanical specifications

Dimensions	79 millimeters (mm) long x 82 mm wide x 25 mm high	
USB cable length	3 meters max	
User connection length	3 meters max	

# Main connector and pin out

Table 4-19. Main connector specifications

Co	onnector type	Screw terminal
W	ire gauge range	16 AWG to 30 AWG

#### 4-channel differential mode

Pin	Signal Name	Pin	Signal Name	
1	CH0 IN HI	21	Port A0	
2	CH0 IN LO	22	Port A1	
3	AGND	23	Port A2	
4	CH1 IN HI	24	Port A3	
5	CH1 IN LO	25	Port A4	
6	AGND	26	Port A5	
7	CH2 IN HI	27	Port A6	
8	CH2 IN LO	28	Port A7	
9	AGND	29	GND	
10	CH3 IN HI	30	PC+5V	
11	CH3 IN LO	31	GND	
12	AGND	32	Port B0	
13	D/A OUT 0	33	Port B1	
14	D/A OUT 1	34	Port B2	
15	AGND	35	Port B3	
16	+2.5VREF	36	Port B4	
17	GND	37	Port B5	
18	TRIG IN	38	Port B6	
19	SYNC	39	Port B7	
20	CTR	40	GND	

# 8-channel single-ended mode

Pin	Signal Name	Pin	Signal Name	
1	CH0 IN	21	Port A0	
2	CH1 IN	22	Port A1	
3	AGND	23	Port A2	
4	CH2 IN	24	Port A3	
5	CH3 IN	25	Port A4	
6	AGND	26	Port A5	
7	CH4 IN	27	Port A6	
8	CH5 IN	28	Port A7	
9	AGND	29	GND	
10	CH6 IN	30	PC+5V	
11	CH7 IN	31	GND	
12	AGND	32	Port B0	
13	D/A OUT 0	33	Port B1	
14	D/A OUT 1	34	Port B2	
15	AGND	35	Port B3	
16	+2.5VREF	36	Port B4	
17	GND	37	Port B5	
18	TRIG IN	38	Port B6	
19	SYNC	39	Port B7	
20	CTR	40	GND	





# **Product Service**

#### **Diagnosis and Debug**

CyberResearch, Inc. maintains technical support lines staffed by experienced Applications Engineers and Technicians. There is no charge to call and we will return your call promptly if it is received while our lines are busy. Most problems encountered with data acquisition products can be solved over the phone. Signal connections and programming are the two most common sources of difficulty. CyberResearch support personnel can help you solve these problems, especially if you are prepared for the call.

To ensure your call's overall success and expediency:

- 1) Have the phone close to the PC so you can conveniently and quickly take action that the Applications Engineer might suggest.
- Be prepared to open your PC, remove boards, report back-switch or 2) jumper settings, and possibly change settings before reinstalling the modules.
- 3) Have a volt meter handy to take measurements of the signals you are trying to measure as well as the signals on the board, module, or power supply.
- 4) Isolate problem areas that are not working as you expected.
- 5) Have the source code to the program you are having trouble with available so that preceding and prerequisite modes can be referenced and discussed.
- 6) Have the manual at hand. Also have the product's utility disks and any other relevant disks nearby so programs and version numbers can be checked.

Preparation will facilitate the diagnosis procedure, save you time, and avoid repeated calls. Here are a few preliminary actions you can take before you call which may solve some of the more common problems:

- 1) Check the PC-bus power and any power supply signals.
- 2) Check the voltage level of the signal between SIGNAL HIGH and SIGNAL LOW, or SIGNAL+ and SIGNAL-. It CANNOT exceed the full scale range of the board.
- 3) Check the other boards in your PC or modules on the network for address and interrupt conflicts.
- 4) Refer to the example programs as a baseline for comparing code.

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# Warranty Notice

CyberResearch, Inc. warrants that this equipment as furnished will be free from defects in material and workmanship for a period of one year from the confirmed date of purchase by the original buyer and that upon written notice of any such defect, CyberResearch, Inc. will, at its option, repair or replace the defective item under the terms of this warranty, subject to the provisions and specific exclusions listed herein.

This warranty shall not apply to equipment that has been previously repaired or altered outside our plant in any way which may, in the judgment of the manufacturer, affect its reliability. Nor will it apply if the equipment has been used in a manner exceeding or inconsistent with its specifications or if the serial number has been removed.

CyberResearch, Inc. does not assume any liability for consequential damages as a result from our products uses, and in any event our liability shall not exceed the original selling price of the equipment.

The equipment warranty shall constitute the sole and exclusive remedy of any Buyer of Seller equipment and the sole and exclusive liability of the Seller, its successors or assigns, in connection with equipment purchased and in lieu of all other warranties expressed implied or statutory, including, but not limited to, any implied warranty of merchant ability or fitness and all other obligations or liabilities of seller, its successors or assigns.

The equipment must be returned postage prepaid. Package it securely and insure it. You will be charged for parts and labor if the warranty period has expired.

#### **Returns and RMAs**

If a CyberResearch product has been diagnosed as being non-functional, is visibly damaged, or must be returned for any other reason, please call for an assigned RMA number. The RMA number is a key piece of information that lets us track and process returned merchandise with the fastest possible turnaround time.

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In most cases, a returned package will be refused at the receiving dock if its contents are not known. The RMA number allows us to reference the history of returned products and determine if they are meeting your application's requirements. When you call customer service for your RMA number, you will be asked to provide information about the product you are returning, your address, and a contact person at your organization.

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