



DVP04PT-H DVP-EH Platinum Temperature Sensors Instruction Sheet

1 WARNING

- A Please carefully read this instruction thoroughly prior to use the DVP04PT-H.
- In order to prevent electric shock, do not touch the terminals or conduct any maintenance while power to the PLC is ON. Do NOT open the PLC. Only qualified personel or Delta staff is allowed to conduct any internal electrical work on the PLC.
- This is an OPEN-TYPE device, and was certified to meet the IEC 61131-2 (UL 508) safety requirements when installed in an enclosure.
- The DVP04PT-H must be kept under the environment away from high temperatures, high humidity, exceessive vibration, corrosive gases, liquids, airborne dust, and metallic particles.
- ⚠ Do not apply AC power to any of the input/output terminals, or it may damage the DVP04PT-H.
- ⚠ Make sure that the DVP04PT-H is properly grounded ⊕, to prevent any electromagnetic noise.
- riangle Use wires with resistance when connect the platinum resistance thermister (RTD) to PLC.
- A Please keep the wires as short as possible when connecting the RTD to PLC, and keep power wires as far away as possible from I/O wires to prevent noise interference.

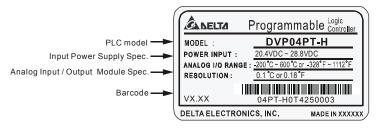
2

INTRODUCTION

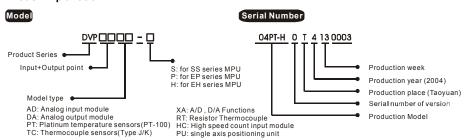
2.1 Model Explanation and Peripherals

- Thank you for choosing DELTA DVP PLC Series. DVP04PT-H allows the connection of four platinum temperature sensors (PT100 3-WIRE 100 Ω 3850 PPM/°C (DIN 43760 JIS C1604-1989)). The DVP-PLC EH MPU converts the sensors input into a 14 bit digital signal, and then be manipulated by using TO and FROM instructions in the ladder logic program. There are 49 Controlled Registers (CR, each register has 16 bits) in each module.
- Software version DVP04PT-H platinum temperature sensors can be updated via RS-485 communication.
- DVP04PT-H displays both Centigrade and Fahrenheit. The input resolution for Centigrade is 0.1 degrees and for Fahrenheit is 0.18 degrees.

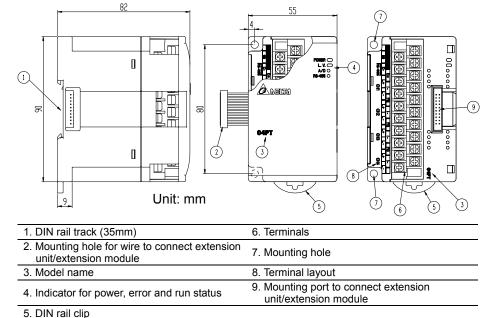
■ Nameplate Explanation



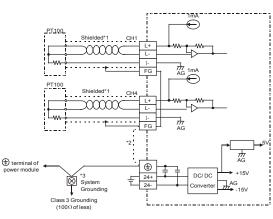
■ Model Explanation



2.2 Product Profile and Outline



2.3 External wiring



- Note 1: Use only the wires that are packed with the temperature sensor (PT 100) for analog input and separate from other power line or any wire that may cause noise. Please use 3wire for PT 100
- Note 2: Terminal FG is a ground location for noise suppression.
- Note 3: Please connect power supply module terminal and DVP04PT-H platinum temperature sensors module terminal to system earth ground or connect it to machine cover.

Warning: DO NOT connect wires to the No Connection (•) terminals.

3

STANDARD SPECIFICATIONS

3.1 Function Specifications

Platinum Temperature Module

(04PT)	Centigrade (°C)	Fahrenheit (°F)								
Power supply voltage	24 VDC (20.4VDC~28.8VDC) (-15%~+20%)									
Analog input channel	4 channels per module									
Sensors type	3-WIRE PT100 Ω 3850 PPM/°C(DIN 43760 JIS C1604-1989)									
Current excitation	1mA									
Temperature input range	-200°C~600°C	-328°F~1112°F								
Digital conversion range	K-2000~K6000	K-3280~K11120								
Resolution	14 bits (0.1°C)	14 bits (0.18°F)								
Overall accuracy	$\pm 0.5\%$ of full scale of 25°C(77°F), $\pm 1\%$ of full scale during 0~55°C (32~131°F)									
Response time	200 ms x channels									
Isolation Method	Isolation between digital and analog circuitry. But no isolation between channels.									
Digital data format	2's complement of 16-bit, (13 Significant Bits)									
Average function	Yes (CR#2~CR#5 may be set and the range is K1~K4096)									
Self diagnostic function	Upper bound and lower bound detection per channel									
Communication mode (RS-485)	Yes, either ASCII or RTU modes, communication rate can be 4800 /9600 /19200 /38400 /57600 /115200. Communication format of ASCII mode is 7Bit, even bit, 1 stop bit (7 E 1). Communication format of RTU mode is 8Bit, even bit, 1 stop bit (8 E 1). When connecting to PLC MPU in series, RS-485 can't be used. The RS-485 is disabled when the DVP04PT-H is connected in series to an MPU (use the RS485 on MPU).									
Connection to a DVP-PLC MPU in series	When DVP04PT-H modules are connected to an MPU, the modules are numbered from 0 – 7. 0 is the closest and 7 is the furthest to the MPU. 8 modules is the max and they do not occupy any digital I/O points of the MPU.									

3.2 Other Specification

Download from Www.Somanuals.com. All Manuals Search And Download.

Power Specification Maximum Power Consumption 2W at 24 VDC (20.4VDC~28.8VDC) (-15 % ~ + 20%)

	Environment Condition
Environment Condition	Follow the DVP-PLC MPU.
Static Electricity Prevention	All places between terminals and ground comply with the spec

4

CR (CONTROLLED REGISTER)

DV	P04PT-H	pla	atinum	temperature sensors						Expla	natio	n						
CB	RS-485 Parameter			Register name	b15 b14	b13	b12	b11	b10 b9	b8	b7	b6	b5	b4	b3	b2	b1	b(
#0	address H 4064	\cap	R	Model type	System	used	data	length	n is 8bits	(h7~h	0) D\	/P04	PT-H	mode	el code	e = H	0402	느
#1		_		Reserved			,			(-,							-
#2	H 4066	0	R/W	CH1 average number														
#3	H 4067	0	R/W	CH2 average number	The nur on chan				idings us	ed for	the c	alcula	ation	of "av	erage	e" tem	pera	tur
#4	H 4068	0	R/W	CH3 average number					96 and fa	ctory s	etting	n is K	10					
#5	H 4069	0	R/W	CH4 average number	Octung	rango	, 13 1	1140	oo ana ia	Clory .	3Cttill (9 13 11	. 10.					
#6	H 406A	X	R	CH1 average degrees(°C)														
#7	H 406B	X	R	CH2 average degrees(°C)	Average	doar	roos f	or cha	nnels CH	1~CH	A (1	ınit: (1 de	aroo	· C)			
#8	H 406C	\times	R	CH3 average degrees(°C)	Average	uegi	ees i	oi ciia	IIIIeis CI I	1011	4. (C	ariit. C	J. I ue	grees	, C)			
#9	H 406D	X	R	CH4 average degrees(°C)														
#10~				Reserved														
#12	H 4070	Х	R	CH1 average degrees(°F)														
#13	H 4071	X	R	CH2 average degrees(°F)	Average degrees for channels (.H1~(.H4 (unit 0.1 degrees F)													
#14	H 4072	X	R	CH3 average degrees(°F)	<u>(F)</u>													
#15	H 4073	Х	R	CH4 average degrees(°F)	İ													
#16~		\vee	R	Reserved Present temperature of														
#18	H 4076	$^{\wedge}$	R	CH1 (°C) Present temperature of														
#19	H 4077	$^{\wedge}$	R	CH2 (°C) Present temperature of	Present	temp	eratu	re of c	hannels (CH1~(CH4. ((unit:	0.1 d	egree	es C)			
#20	H 4078	\langle	R	CH3 (°C) Present temperature of														
#21 #22~	H 4079	\wedge	15	CH4 (°C) Reserved														_
		X	R	Present temperature of														_
#24	H 407C	\sim	R	CH1 (°F) Present temperature of														
#25	H 407D	$^{\wedge}$	R	CH2 (°F) Present temperature of	Present temperature of channels CH1~CH4. (unit: 0.1degrees F)													
#26	H 407E	$^{\wedge}$	R	CH3 (°F) Present temperature of														
#27 #28~	H 407F	$^{\wedge}$	10	CH4 (°F) Reserved														
#30	H 4082	X	R	Error status	Data re	aister	store	s the e	error statu	ıs. Re	fer to	the fa	ault co	ode c	hart fo	or deta	ails.	
#31	H 4083	0	R/W	Communication address	RS-485	comr	nunic	ation a	address.									_
#32	H 4084		R/W	setting Communication baud rate					and facto te (4800,				3400	5760	0 and	11152	200 h	ns
				setting	Commu b0: 480 b1: 960 b2: 192 b3: 384 b4: 576 b5: 115 b6~b13 b14: sw b15: R1	nication of the control of the contr	on for s (bit/s s (bit/s s (bit s (bit s (bit s (bit s (bit s erved between	mat of sec). /sec). /sec). /sec). it/sec). it. en low	bit and h	etting	8Bit, e	even	bit, 1	Stop	bit (8	E 1).		
#33	H 4085	0	R/W	Reset to factory setting					b10 b9	b8		b6	b5	b4	b3		b1	b
					Example 1. b0 Re 2. b1 Re 3. b2: S Definitio 1. b12 conta 2. b13 conta 3. b14 conta 4. b15	e: Set esserve esserve et to on of E corres act ha corres act ha corres act ha	ed ed ed 1 and ERR L spond as no spond as	PLC v LED: b Is to C connection Is to C connection Is to C connection Is to C connection Is to C	will be res 12~b15= H1: who ction, ER CH2: whe ction, ER CH3: whe ction, ER	eet to f 1111(f en b12 R LEC n b13 R LEC n b14 R LEC n b15	actory 2=1, s) flash =1, s) flash =1, s) flash =1, s	cale cale cale cale cale cale cale cale	tings. ings) excee	eds th	e ran e ran	ge or ge or ge or	exte	erna
#34	H 4086		P	Software version					ction, ER				ا ما	0104	- 200	sion 1	Λ^	
#34		\cup	R	Software version	Display	SUILM	are ve	ersion	in hexad	ecima	ı. ⊑ X	amp	ie. H	UIUA	- vers	รเบก 1	.uA.	_
#JO~₹		me	ans late	System used ched.														_
	X R n	me nea	ans no	t latched. I data by using FROM instru e data by using TO instruction			5.											

Explanation:

- 1. CR#0: The PLC model type.
- 2. CR#1, CR#10, CR#11, CR#16, CR#17, CR#22, CR#23, CR#28, CR#29 are reserved.
- 3. CR#2 ~ CR#5: Used to set the number piece of input readings used for the average temperature calculation. The available range is K1~K4096 and factory setting is K10.
- 4. CR#6 to CR#9: The average temperature (c). Temperature is calculated by averaging multiple pieces temperature readings. Example: If CR#2 is 10, the temperature in CR#6 will be the average of the last 10 readings on CH1.
- 5. CR#12 to CR#15: The average temperature (c). Temperature is calculated by averaging multiple pieces temperature readings. Example: If CR#2 is 10, the temperature in CR#12 will be the average of the last 10 readings on CH1.
- 6. CR#18 ~ CR#21: display the present temperature (°C) of CH1~CH4 input signal.

- 7. CR#24 ~ CR#27: display the present temperature (°F) of CH1~CH4 input signal.
- 8. CR#30 is the fault code register. Refer to the chart below

Fault description	Content	b15~b8	b7	b6	b5	b4	b3	b2	b1	b0			
Power source abnormal	K1(H1)		0	0	0	0	0	0	0	1			
Analog input value error	K2(H2)	1	0	0	0	0	0	0	1	0			
Setting mode error	K4(H4)		0	0	0	0	0	1	0	0			
Offset/Gain error	K8(H8)	Reserved	0	0	0	0	1	0	0	0			
Hardware malfunction	K16(H10)	Reserved	0	0	0	1	0	0	0	0			
Digital range error	K32(H20)		0	0	1	0	0	0	0	0			
Average times setting error	K64(H40)		0	1	0	0	0	0	0	0			
Instruction error	K128(H80)		1	0	0	0	0	0	0	0			
	Note: Each fault code has the corresponding bit (b0~b7). Two or more faults may happen at the same time. 0 means normal and 1 means fault happened.												

- 9. CR#31: RS-485 communication address. Setting range is 01~255 and factory setting is K1.
- 10. CR#32: RS-485 communication baud rate: 4800, 9600, 19200, 38400, 57600 and 115200. b0:4800bps, b1:9600bps (factory setting), b2:19200bps, b3:38400 bps, b4:57600 bps, b5:115200 bps, b6~b13: Reserved, b14: switch between low bit and high bit of CRC code (only for RTU mode) b15=0: ASCII mode, b15=1: RTU mode. Communication format for ASCII mode is 7Bit, even bit, 1 stop bit (7 E 1), while for RTU mode is 8Bit, even bit, 1 stop bit (8 E 1).
- 11. CR#33: b0~b11: Used to reset the settings of CH1~CH4 to factory defaults.

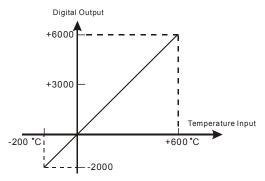
b12~b15: defined the ERR LED, factory setting is b12~b15=1111.

- 12. CR#34: software version.
- 13. CR#35~ CR#48: Reserved for internal system use.
- 14. The corresponding parameters address H4064~H4095 of CR#0~CR#48 are provided for users to read/write data via RS-485 communication.
 - Baud rate can be 4800, 9600, 19200, 38400, 57600, 115200bps.
 - MODBUS communication protocol can be either ASCII or RTU mode. Communication format for ASCII mode is 7Bit, even bit, 1 stop bit (7 E 1), while for RTU mode is 8Bit, even bit, 1
 - Function code: 03H read data from register.

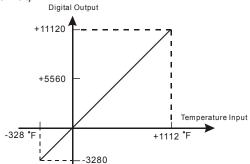
06H write 1pcs WORD into register. 10H write multiple WORD into register.

TEMPERATURE/DIGITAL CHARACTERISTIC CURVE

Temperature mode: (Centigrade)



Temperature mode: (Fahrenheit)

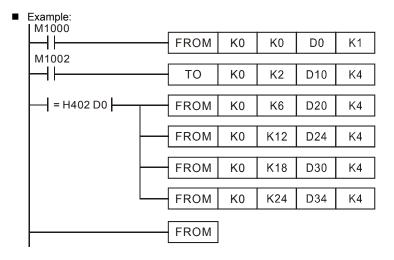


INITIAL PLC START-UP

- LED display:
 - 1. Upon power-up, the ERROR LED will light on for 0.5 seconds the POWER LED will light on continuously
 - 2. POWER LED on and ERROR LED off means No Error.

Low Voltage error (lower than 19.5V), ERROR LED will blink continuously till the power supply goes above 19.5V.

- DVP04PT-H is connected to PLC MPU in series = RUN LED on MPU will be lit and A/D LED or D/A LED should blink.
- After receiving the first RS-485 instruction the A/D LED or D/A LED will blink.
- If the input or output exceeds the upper or lower bounds, then the ERROR LED will blink.



Explanation

- Read the model type of extension module K0 (should be H0402 for DVP04PT-H model type).
- The average values of CH1~CH4 saved in D10~D13 are written into CR#2~CR#5.
- For DVP04PT-H model. The read average temperature (°C) of CH1~CH4 (4 data) from CR#6~CR#9 and saved to D20~D23.
- The read average temperature (°F) of CH1~CH4 (4 data) from CR#12~CR#15 and saved into
- The read present temperature (°c) of CH1~CH4 (4 data) from CR#18~CR#21 and saved into
- The read present temperature (°F) of CH1~CH4 (4 data) from CR#24~CR#27 and saved into

7

RELATED INSTRUCTIONS EXPLANATION

API											sne	ecial module CR	cable m	nodel					
78	78 D FROM P m m D n Read sp									opt	ES EP								
70	∐-	1				•	T Gala										✓	✓	✓
	Bit device Word device													<u></u>					
	Х	Υ	М	S	K	Н	KnX	KnY	KnM	KnS	Т	С	D	Ε	F	16-bit instruction (9 S	STEP		
m ₁					*	*										FROM Continuous F	ROM	P Puls	se cution
m_2					*	*													
D								*	*	*	*	*	*	*	*	32-bit instruction (17	STE	PS)	
n					*	*					L					DFROM Continuous execution	DFRC	MP Pul	se ecution
		No	ote:	Th El- Th	e us 1: 0- e us	sag -254 sag	e rand 4. e rand	ge of ge of	opera	nd m_1 ind m_2 : nd m_2 : 2).	ES	S/E	P: (8,	• Flag: When M1 to enable FROM/TC below for	inter). Re	rupt dur fer to th	ring

ES series model doesn't support pulse

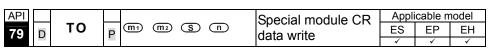
execution instruction (FROMP, DFROMP).

Command

Program

- m1: the module number you are probing. m2: the number of Controlled Registers to be read. D: the data register location for storing data. : the number of CRs to read at one time
- ◆ DVP-series PLC uses this instruction to read CR data of each special module.
- D: When assigning bit operand, K1~K4 are used for 16-bit and K5~K8 are used
 - Please refer the following footnote for calculating of special module number.
- Read the content of CR#24 and CR#25 of module#0 and save it into D0 and D1 when n=2.
- Instruction will be executed when X0=ON. However, nothing will occur and the stored data has no change when X0=OFF.





	В	it c	levi	ce				W	ora a	evice						40 bit in atmostic or (0 OTEDO)
	Χ	Υ	М	S	Κ	Н	KnX	KnY	KnM	KnS	Τ	С	D	Ε	F	16-bit instruction (9 STEPS) Continuous TOP Pulse
m_1					*	*										TO execution TOP execution
m_2					*	*										execution execution
S					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (17 STEPS)
n					*	*										
•	 Note: The usage range of operand m₁ is 0~7. 															DTO execution DTOP Pulse execution
				The EH The 1~ ES	e u: l: 0 e u: (49 s se	sag -25 sag -m2 ries	e ran 4. e ran 2), EF does	ge of ge of I: 1~(2	opera opera 255-m suppo	nd m ₂ nd n: 2).	ES	S/I	EP: P: r)=	.8,	 Flag: When M1083=On, it allows to insert interrupt during FROM/TO. Refer to following for detail.

Command Explanation

- $\overline{m_1}$: the module number you are probing. $\overline{m_2}$: the number of Controlled Registers to be written to. S: the data to write. n: the number of CR to be
- ♦ DVP-series PLC uses this instruction to write data to Controlled Registers of special modules
- S: When assign the bit operand, K1~K4 are used for 16-bit and K5~K8 are

Program Example

- Using the 32-bit instruction DTO. The program will write D11 and D10 into CR#3 and CR#2 of special module#0. DTO only allows one group of data to be written at
- ◆ The instruction is executed when X0=ON. Nothing will occur and the stored data will have no change when X0=OFF.



Footnote

Applicable model

- The rules for adding multiple special modules to a Main Processing Unit:
 - m1: The maximum number of special modules attached to an MPU is 8. The module closest to the MPU is 0 and the module furthest from the MPU is 7.
 - m2: The number of Controlled Registers (CR) built in is 49. (#0~#48).
 - FROM/TO instruction read/write one CR at a time, while DFROM/DTO instruction read/write two CR at a time. Example below:



(Access16-bit if n=2, or 32-bit if n=1. Same controlled registers are accessed) Assigned Assigned Assigned Assigned CR CR Equipment Equipment D0 CR#5 D0 CR#5 D1 CR#6 D1 CR#6 D2 CR#7 D2 CR#7 D3 CR#8 D3 CR#8

D4

D5

16-bit command when n=6

D4

D5

CR#9

CR#10

32-bit command when n=3

CR#9

CR#10

- ♦ In ES series models, flag M1083 is not provided. When FROM/TO instruction is executed, all interrupts (including external or internal interrupt subroutines) will be disabled. All interrupts will be executed after FROM/TO instruction is completed. Besides, FROM/TO instruction also can be executed in the interrupt subroutine.
- ♦ The function of the flag M1083 (FROM/TO mode exchange) provided in EP/EH
 - a. When M1083=Off, all interrupts (including external or internal interrupt subroutines) will be disabled when FROM/TO instruction is executed. The Interrupts will resumed after FROM/TO instruction complete. Please be advised FROM/TO instruction can be executed in the interrupt subroutine.
 - When M1083=On, if an interrupt enable occurs while FROM/TO instruction are executing, the interrupt FROM/TO instruction will be blocked till the requested interrupt finish. Unlike M1080 off situation, FROM/TO instruction cannot be executed in the interrupt subroutine.

Download from Www.Somanuals.com. All Manuals Search And Download.

Free Manuals Download Website

http://myh66.com

http://usermanuals.us

http://www.somanuals.com

http://www.4manuals.cc

http://www.manual-lib.com

http://www.404manual.com

http://www.luxmanual.com

http://aubethermostatmanual.com

Golf course search by state

http://golfingnear.com

Email search by domain

http://emailbydomain.com

Auto manuals search

http://auto.somanuals.com

TV manuals search

http://tv.somanuals.com